

**Amendments to the Claims:**

The following listing of claims will replace all prior versions, and listings, of claims in the application:

1. (Currently Amended) A roller mechanism for transporting loads over a surface, comprising:
  - a body;
  - at least one roller assembly that permits the body to move in at least one translational direction, the roller assembly being rotatably connected to the body; and
  - a lifting mechanism attached to the body such that the body is selectively rotatable relative to the lifting mechanism and a load when the load is placed on the roller mechanism;

wherein the lifting mechanism can be operated to lift the roller assemblies out of contact with the surface; and

wherein the lifting mechanism has a retracted state and an extended state and includes a foot which is not in contact with the surface when the lifting mechanism is in the retracted state, but which contacts the surface when the lifting mechanism is in the extended state.
2. (Original) The roller mechanism of claim 1, wherein the lifting mechanism includes at least one projection and the body includes at least one detent that receives the at least one projection; and wherein the at least one projection and the at least one detent maintain the body in a fixed rotatable position relative the lifting mechanism.
3. (Original) The roller mechanism of claim 2, wherein the body is rotatable relative to the lifting mechanism when the at least one projection is not engaged with the at least one detent.
4. (Original) The roller mechanism of claim 1, wherein

the body includes a top wall; and

the lifting mechanism comprises:

a hydraulic cylinder that extends through the top wall of the body, and  
a structural member that (a) is attached to or integral with an outside surface of the hydraulic cylinder, (b) is below the top wall of the body and (c) selectively engages the top wall of the body.

5. (Original) The roller mechanism of claim 4, wherein the structural member contacts a lower surface of the top wall after the hydraulic cylinder extends a predetermined distance.

6. (Original) The roller mechanism of claim 5, wherein the lifting mechanism includes at least one projection and the body includes at least one detent that receives the at least one projection; wherein the at least one projection and the at least one detent maintain the body in a fixed rotatable position relative the lifting mechanism when engaged and the at least one projection is disengaged from the at least one detent when the hydraulic cylinder extends the predetermined distance.

7. (Original) The roller mechanism of claim 4, wherein the structural member is a lift ring.

8. (Original) The roller mechanism of claim 4, wherein the roller assembly is a chain roller assembly.

9. (Cancelled)

10. (Currently Amended) The roller mechanism of ~~claim 9~~claim 1, wherein when the lifting mechanism is in the extended state, the lifting mechanism supports the body and the at least one roller assembly above the surface.

11. (Currently Amended) A roller mechanism for transporting loads over a surface, comprising:

a body;  
at least one roller assembly that permits the body to move in at least one translational direction, the roller assembly being rotatably connected to the body; and  
a lifting mechanism attached to the body such that the body is selectively rotatable relative to the lifting mechanism and a load when the load is placed on the roller mechanism and the lifting mechanism can be operated to lift the body and the at least one roller assembly from the surface;

wherein the lifting mechanism has a retracted state and an extended state and includes a foot which is not in contact with the surface when the lifting mechanism is in the retracted state, but which contacts the surface when the lifting mechanism is in the extended state.

12. (Original) The roller mechanism of claim 11, wherein the lifting mechanism includes at least one projection and the body includes at least one detent that receives the at least one projection; and wherein the at least one projection and the at least one detent maintain the body in a fixed rotatable position relative the lifting mechanism.

13. (Original) The roller mechanism of claim 12, wherein the body is rotatable relative to the lifting mechanism when the at least one projection is not engaged with the at least one detent.

14. (Original) The roller mechanism of claim 11, wherein  
the body includes a top wall; and  
the lifting mechanism comprises:  
a hydraulic cylinder that extends through the top wall of the body, and  
a structural member that (a) is attached to or integral with an outside surface of the hydraulic cylinder, (b) is below the top wall of the body and (c) selectively engages the top wall of the body.

15. (Original) The roller mechanism of claim 14, wherein the structural member contacts a lower surface of the top wall after the hydraulic cylinder extends a predetermined distance.

16. (Original) The roller mechanism of claim 15, wherein the lifting mechanism includes at least one projection and the body includes at least one detent that receives the at least one projection; and wherein the at least one projection and the at least one detent maintain the body in a fixed rotatable position relative the lifting mechanism when engaged and the at least one projection is disengaged from the at least one detent when the hydraulic cylinder extends the predetermined distance.

17. (Currently Amended) A roller mechanism for transporting loads over a surface comprising:

a body;

at least one roller assembly that permits the body to move in a translational direction, the at least one roller assembly being rotatably connected to the body; and  
a lifting mechanism having a retracted state in which the lifting mechanism does not contact the surface and an extended state in which the lifting mechanism contacts the surface and supports the body and the roller assembly above the surface;

wherein the body and the roller assembly are rotatable relative to the lifting mechanism and a load when the load is placed on the roller mechanism when the body and the roller assembly are not in contact with the surface; and

wherein the lifting mechanism includes a foot which is not in contact with the surface when the lifting mechanism is in the retracted state, but which contacts the surface when the lifting mechanism is in the extended state.

18. (Currently Amended) The roller mechanism of claim 17, wherein the lifting mechanism includes:

a hydraulic cylinder,  
~~a-the foot which selectively engages the surface,~~  
a structural member located within the body, and  
a load bearing surface,  
wherein the foot, structural member and load bearing surface are connected to  
the cylinder.

19. (Original) The roller mechanism of claim 18, wherein the structural member  
engages the body to raise the roller assembly above the surface.

20. (Currently Amended) A method of operating a roller mechanism on a surface,  
the roller mechanism having a body, at least one roller assembly for moving the body in at  
least one translational direction over the surface, the roller assembly being rotatably  
connected to the body, and a lifting mechanism, comprising the steps of:

lifting, with the lifting mechanism, a load that has been placed on the roller  
mechanism by a predetermined distance;

lifting, with the lifting mechanism after the load has been lifted the  
predetermined distance, the load, the body and the at least one roller assembly until the at  
least one roller assembly is out of contact with the surface; and

rotating the body relative to the lifting mechanism and the load;

wherein the lifting mechanism has a retracted state and an extended state and  
includes a foot which is not in contact with the surface when the lifting mechanism is in the  
retracted state, but which contacts the surface when the lifting mechanism is in the extended  
state.